

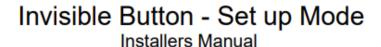
## Dual Inlet Pendulum Installers Manual



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Invisible Button

Press here to get into the set up mode

This screen is the first screen that is displayed when the control unit is energized.

#### Invisible Button

In the top right corner press the screen this will take you into the set up mode.

A red screen will appear then select which Inlet you wish to set up

P1



## Inlet A Set Up Installers Manual

# Push "Set A" to be set up Inlet A



Step 1 Prox Set up





Move the arm to the middle over the home position prox, when this occurs the "OFF" button will switch to "ON"

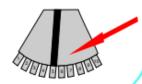
If not see prox setup page

Then move to next step

Step 2 Motor Set up Press REV the arm should move towards Port 1

Note: If the arm is moving in the wrong direction, cross motor leads.
Then repeat Step 2

If OK move to next step



P2

### Inlet A Set Up Installers Manual

Step 3 Encoder Set up When pressing REV the Encoder numbers should be counting down

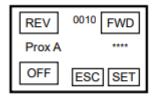
If OK move to next step

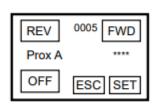
(If the Encoder Value is negative the Encoder Value will appear to be going up) See Fig. below

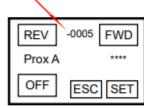
Note: If the Encoder values are counting in the wrong direction, cross wires X0 and X1
Then repeat Step 3

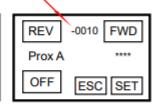
Example the Encoder values below are counting down but appear to be increasing

Notice the minus sign



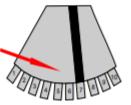






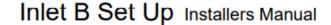
Step 4 Push and hold FWD move the arm to Port 7 (should pass the home position prox)

Now see test page



Do not push the Set button use the ESC

**P3** 





Step 1

Step 2

Prox Set up

Move the arm to the middle over the home position prox, when this occurs the "OFF" button will switch to "ON"

If not see prox setup page

Then move to next step

Press REV the arm should move towards Port 1

Motor Set up

Note: If the arm is moving in the wrong direction, cross motor leads. Then repeat Step 2

If OK move to next step

Step 3 Encoder Set up When pressing REV the Encoder numbers should be counting down

If OK move to next step



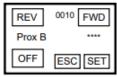
(If the Encoder Value is negative the Encoder Value will appear to be going up) See Fig below

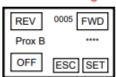


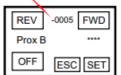
Note: If the Encoder values are counting in the wrong direction, cross wires X3 and X4

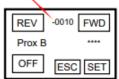
Then repeat Step 3

Example the Encoder values below are counting down but appear to be increasing Please look for the minus sign









Do not push the Set button use the ESC

Ρ4

Installers Manual

#### **Errors**

#### **Cross Wire Detection**

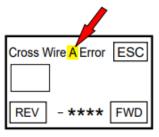
When you see this screen the motor or the encoder has been wired incorrectly.

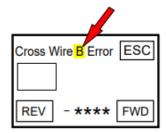
Please notice if Port A or Port B error

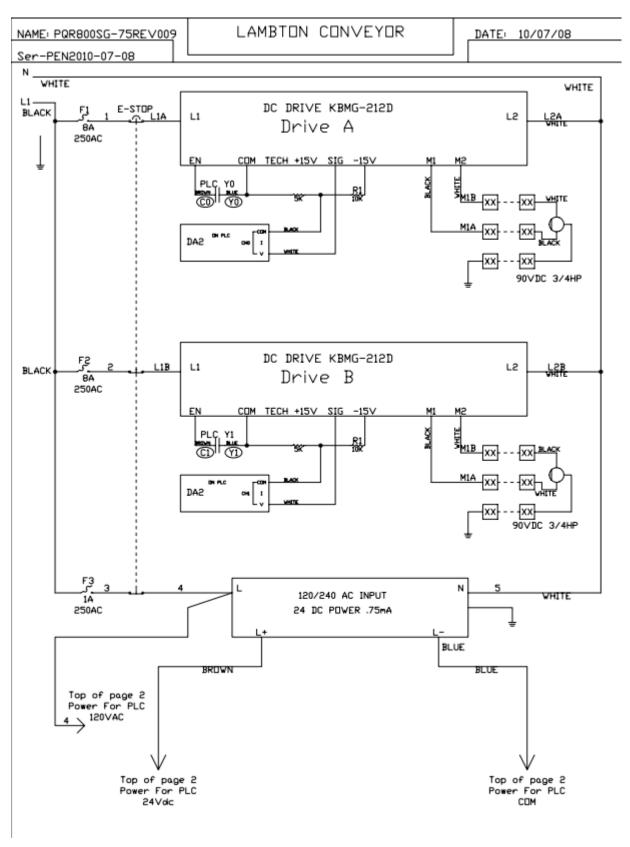
Refer to pages

P2 - Verifying Motor Direction

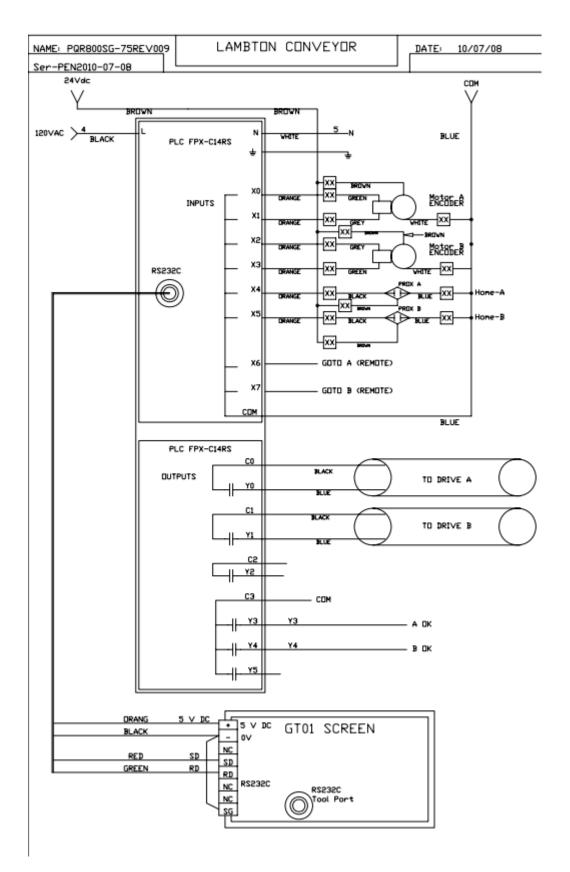
P3 - Verifying Encoder Direction



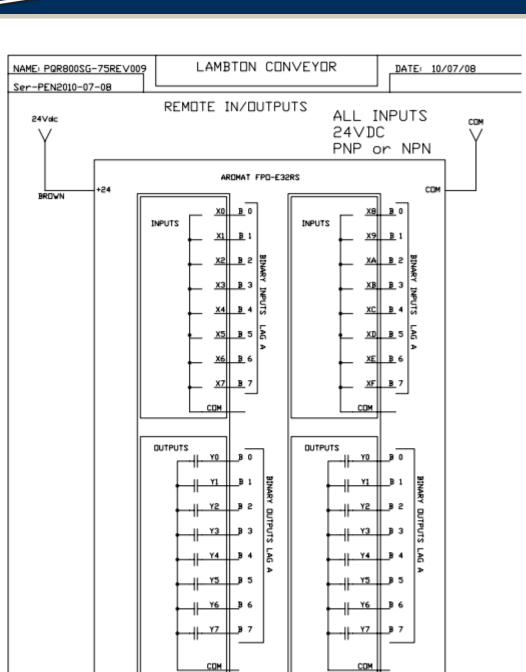




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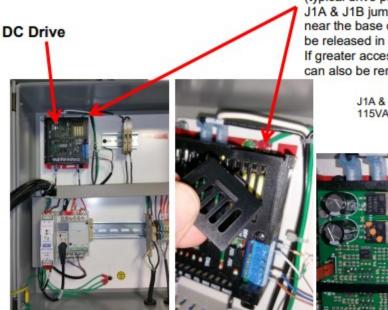


All outputs are Relays 250Vac 2amp

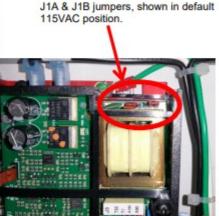
#### INSTRUCTION TO CHANGE AC LINE INPUT VOLTAGE TO 230VAC

115 VAC is the default setting from the factory. To change to 230VAC input voltage, follow the steps outlined below. (Note that Dual Inlet Pendulum Distributors have two DC Drives)

1. Locate J1A & J1B jumpers on the DC Drive



Open the small door on top of the drive (typical drive placement) to reveal the J1A & J1B jumpers. The door has a tab near the base of the drive that needs to be released in order to remove the door. If greater access is needed the face plate can also be removed.



To change input voltage to 230VAC move both jumpers to the inside position, as shown below. No other changes are required.

115VAC JUMPER CONFIGURATION (TYPICAL FACTORY DEFAULT SETTING) 230VAC JUMPER CONFIGURATION

